

HW 4 – Due in Dropbox, 5pm Monday.

The actual Mid-Term will look nearly identical to this in form.

This practice exam is a slightly-modified version of the Midterm given in ECE147B in 2011.

Name _____

ECE 147B

Practice Midterm Exam

Due 5pm, Feb. 13, 2011

- You are allowed one, single-side 8 ½ x 11 sheet of self-prepared notes.
 - Use **must** submit this “Cheat Sheet” with your exam; it will be returned with your graded exam, as is.
 - **No calculators, laptops, or other computing devices are allowed.**
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 /25 Problem 1: Discrete-time controller analysis

 /15 Problem 2: Tustin transformation

 /20 Problem 3: Corresponding s- and z-plane poles

 /20 Problem 4: ZOH effects on a plant, $P(s)$

 /20 Problem 5: State space (continuous time) equations

 /100 TOTAL

Midterm ID number.

Below are two matched random numbers. Tear off the non-taped number and keep it.

We will post exam grades and statistics using these numbers instead of student names, to hide identities.

(Taped side)	<u>TEAR AND KEEP TAB BELOW</u>

1) For this discrete-time transfer fn: $C(z) = \frac{z - 0.96}{z - 0.99}$, with sampling time $T = 0.01$ sec.

2 points a) What is the DC gain?

2 points b) What is the high-frequency gain?

5 points c) At *approximately* what frequency does $C(z)$ have the greatest deviation in phase (i.e., away from 0 degrees phase, on a Bode plot)?

8 points d) Estimate the peak phase shift $C(z)$; that is, the phase shift for a sinusoidal input at the frequency calculated in part c. *You may wish to use the tan function in the Appendix to estimate.*

e) [Problem 1-e is at the top of the next page...]

- 8 points e) Sketch an approximate Bode plot for $C(z)$. Label important details with care. (Please use the blank space below to do this.)

2) You are given the following continuous-time controller:

$$C(s) = 10 \frac{(s + 20)}{(s + 100)}$$

10 points

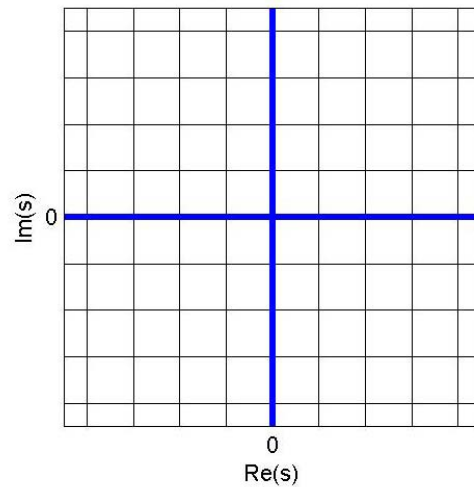
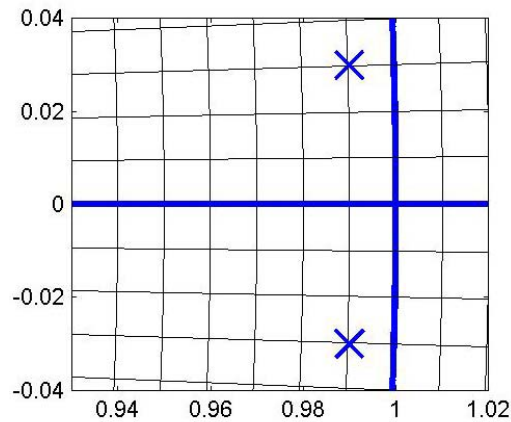
a) Use the Tustin transformation (aka bilinear transformation, or trapezoid rule) to convert $C(s)$ to a discrete-time controller, $C(z)$. Leave the sampling time, T , as a variable.

5 points

b) Now, assume $T=0.001$ seconds. Solve numerically for $C(z)$.

- 3) The figure at left below shows poles (zoomed in on the unit circle) on the z plane for $P(z) = \frac{K}{(z - .99 + .03j)(z - .99 - .03j)} = \frac{K}{z^2 - 1.98z + .981}$, where $T = .001$ seconds

LABEL AXES, to show scale!



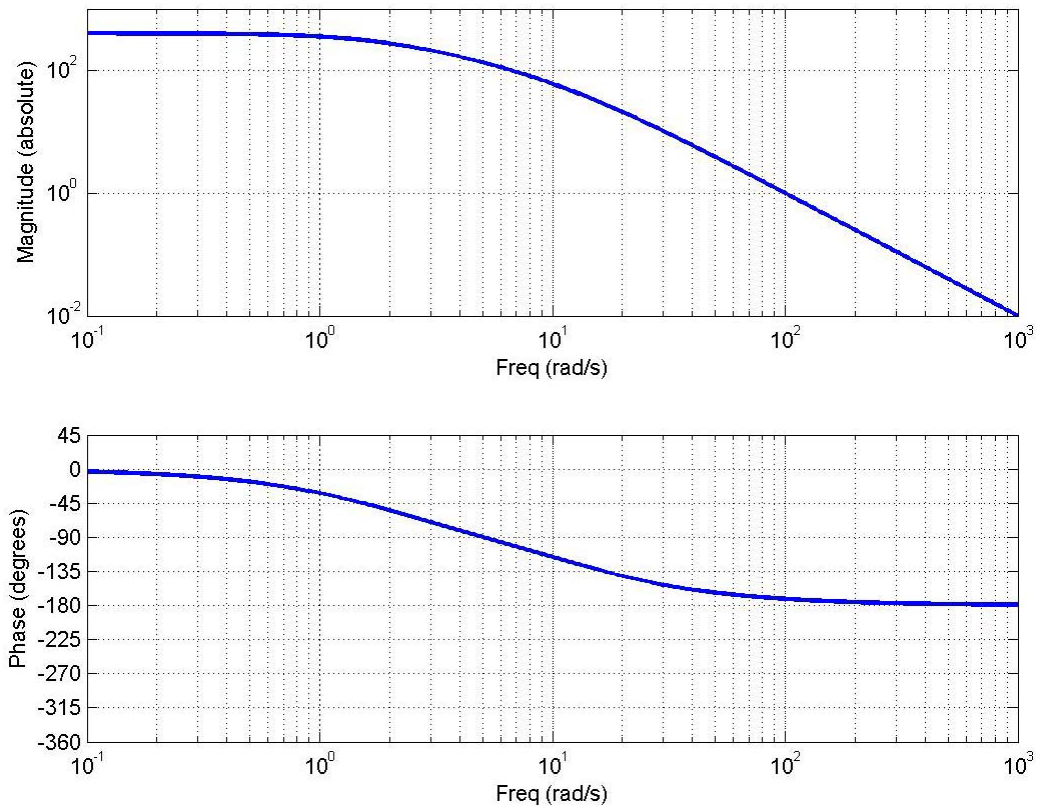
- 5 points a) Plot **approximate** corresponding pole locations on the empty Cartesian axes at the right above, being carefully to label enough of the grid marks on the x and y axes to show scale. (You may or may not find it helpful to complete parts b and/or c first...)
- 3 points b) Calculate the corresponding locations for poles on the s plane using the forward Euler integration approximation. (That is: $s = \frac{z-1}{T}$, which can also be written as $z = Ts + 1$.) [This should be simple, if you use the factored representation of poles of $P(z)$, top left.]
- 3 points c) Demonstrate that the corresponding locations for poles on the s plane using **one** other method (e.g., backward Euler, Tustin **or** matched) are in “**approximately**” the same location.

9 points

3-d) Below, sketch (roughly) a unit step response for $P(z)$. Do not worry about capturing the discrete nature of the plot! Instead, focus on calculating *approximate* values for the following three values, which MUST BE LABELED CLEARLY on your plot:

- i) Final value (Written in terms of K .)
- ii) t_{peak} (Time of maximum overshoot.)
- iii) Maximum percent overshoot

- 4) Below is a Bode plot for some system, $P(s)$, which is part of the sampled-data configuration discussed in class, where a zero-order hold precedes the input and the output are sampled, and where the sampling time is $T=.03$ seconds.



5 points

- a) What is the Nyquist frequency, ω_{Nyquist} , for the system?

6 points

- b) Write a general expression giving the additional lead or lag due to a **half-sample delay** at frequency $\omega = K\omega_{\text{Nyquist}}$, where $0 < K < 1$? (Leave K as a variable in your answer. Parts a and b have nothing to do with the particular Bode plot shown above.)

9 points

- c) On the same axes where phase for $P(s)$ is plotted above, sketch a shifted version to represent the phase of $P(z)$. You may assume the phase is simply shifted by a half-sample delay, as in part b. **Draw only the phase; not gain.** Label these 3 points “A”, “B”, “C”:

- A) Frequency and phase at ω_{Nyquist} . B) Frequency and phase at $\frac{1}{2} \omega_{\text{Nyquist}}$.
 C) Frequency and phase at $\frac{1}{10} \omega_{\text{Nyquist}}$.

- 5) Recall the continuous time state space representation of a dynamic system, given below:

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

In this problem, x , A , B , C , and D are defined as:

$$x = \begin{bmatrix} \theta \\ \dot{\theta} \end{bmatrix} \quad A = \begin{bmatrix} 0 & 1 \\ 12 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

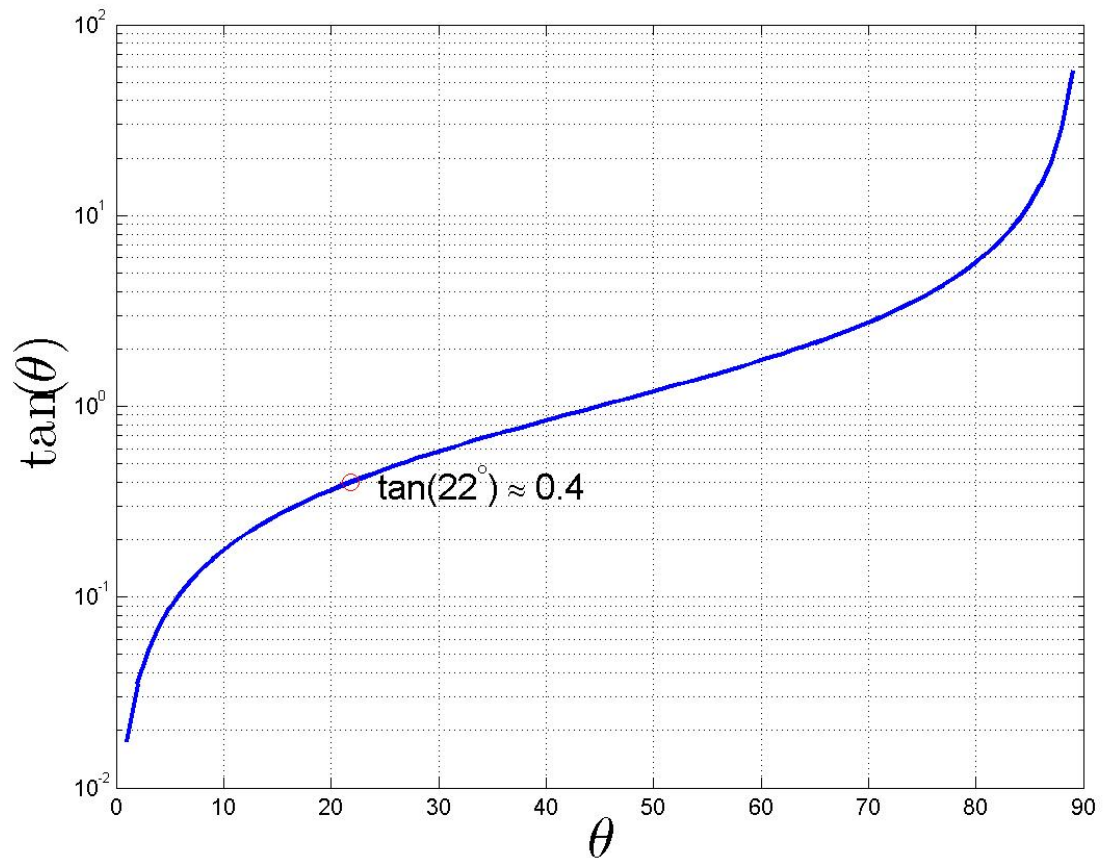
$$C = [3 \quad 0] \quad D = [0]$$

- 4 points a) Write a differential equation relating u to θ .
- 4 points b) What is the transfer function from u to y ? (**Note this is to output, y** ; not to $\theta \dots$)
- 6 points c) Write out the characteristic equation from $\det\{sI - A\} = 0$. (Hint this should match the denominator of the transfer function...) What are the poles of the system?
- 2 points d) Is the open-loop system stable? (Why?)
- 4 points e) What is its final value to a step response?
- Extra
Credit f) Solve for K_1 and K_2 for a feedback regulator of the form

$$u = -BKx$$
to place the poles at $s = -10 \pm 10j$

Appendix: The tangent function.

*Note: This Appendix is likely to appear in the actual Midterm, too, so **learn to use it now** for problems involving phase calculations for both CT and DT transfer functions.*



The examples and figure below illustrate how to use semilog plot above:

- The complex number $5+2j$ has phase: $\text{atan}\left(\frac{2}{5}\right) \approx 22^\circ$.
- The complex number $5-2j$ has phase: $\text{atan}\left(\frac{-2}{5}\right) \approx -22^\circ$.
- The complex number $-5-2j$ has phase: $\text{atan}\left(\frac{-2}{-5}\right) \approx -180^\circ + 22^\circ = -158^\circ$.

