

Today: The Z Transform

Why not
Start up
MATLAB?



Lecture 4

ECE 147B
Digital Control

Reading: FPW 6.3.1, 4.6.1, 4.2.1
or: FV 2.3, 2.5, 2.8, 6.3.3

Topics:

- Definition of Z Transform (Review from Lecture 3)
- Some classic (and important) examples
- Block Diagram Algebra is the same ($G(z)$ vs $G(s)$)
- Properties of the Z Transform
- Tustin with Pre-Warp

HW 1 due TOMORROW! Prelab 2 due Tues.

Next Class: Time response: s-plane vs z-plane.
- FPW: 4.4, 7.3.1
or: - FV: 2.6

(Keep a copy
for yourself.
Solutions out
in lab...)



Focus on
EXAMPLES.
(not tables,
etc...)

→ MATLAB
your
way
thru
class..

teaching the '**Z-TRANSFORM**'...

CT	DT
$G_S = f(s, a, b)$	$G_Z = f(a, b, T)$
$\uparrow \quad \uparrow$ $[1, 2, 3], [4, 5, 6]$	$\uparrow$ $T=0$ or $T=1$

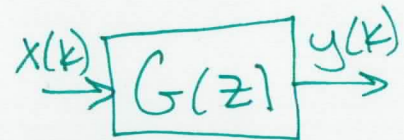
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Definition of Z Transform

Given a sequence of samples, x_k :

$$X(z) \equiv Z\{x(k)\} \equiv \sum_{-\infty}^{\infty} x_k z^{-k}$$

$$\frac{1}{z^k}$$



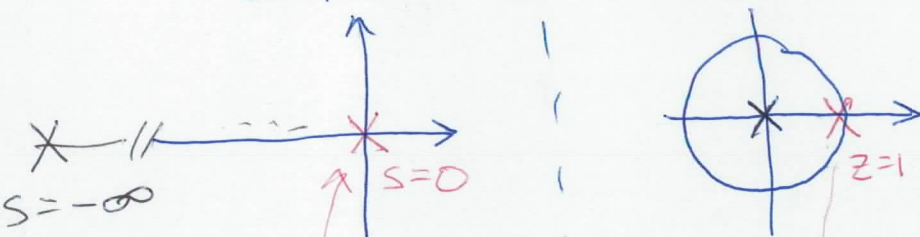
Example:

$$G_1(z) = \frac{Y(z)}{X(z)} = \frac{4z^3 + 2z^2 + 5z + 3}{z^3}$$

$$y(k): \sum y_{k=-3} z^3 + y_{-2} z^2 + y_{-1} z^1 + y_0 z^0$$

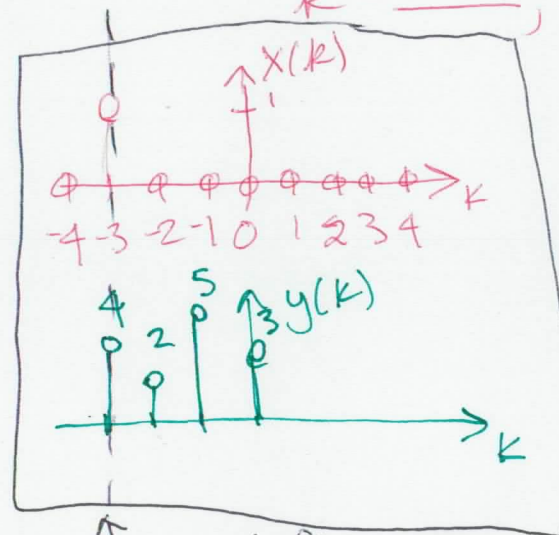
$x(k): x$ is non-zero only @ $k = -3$, $x(k = -3) = 1$
 $x(k \neq -3) = 0$

s-plane vs z-plane



Correspondence.

Deadbeat control: poles @ $z = 0$
 (like $s = -\infty$)



can shift k-axis for both.

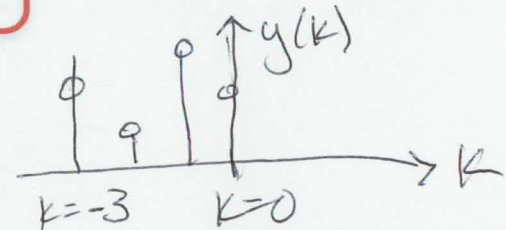
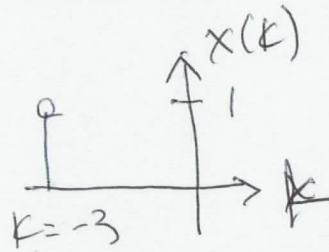
Impulse Response of $G(z)$: Inputs Z-xform is 1

Same Example:

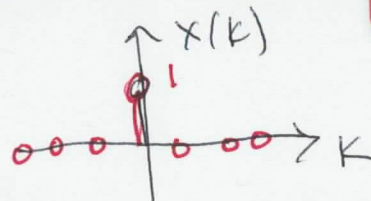
$$G_1(z) = \frac{Y(z)}{X(z)} = \frac{4z^3 + 2z^2 + 5z + 3}{z^3}$$

$$X(z) \equiv Z\{x(k)\} \equiv \sum_{-\infty}^{\infty} x_k z^{-k}$$

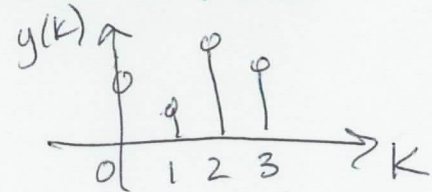
Imagine some $u(k)$ for which $Z(\cancel{x(k)}) = z^3$...What is $y(k)$?



Imagine some $u(k)$ for which $Z(\cancel{x(k)}) = 1$...What is $y(k)$?

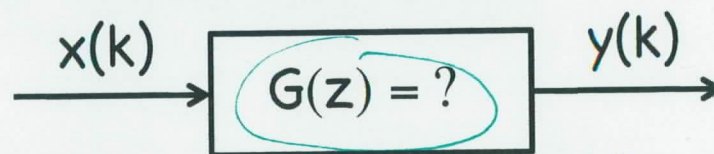


This is an
IMPULSE
in x

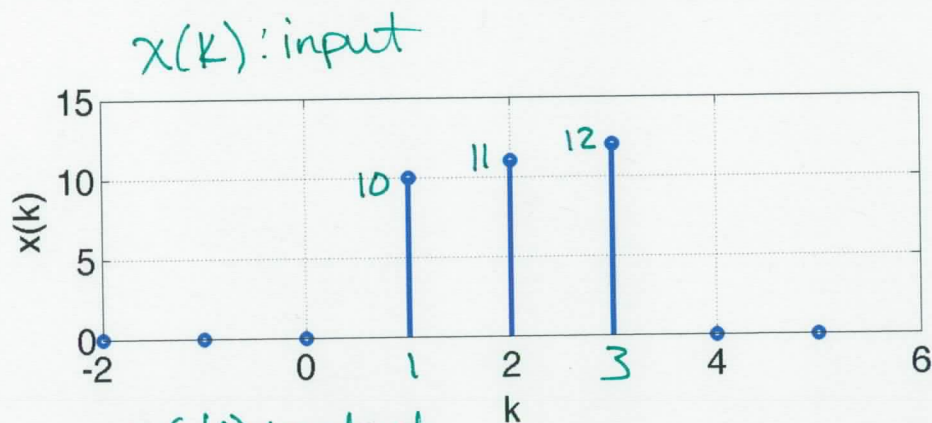


Examples: Find Z xforms for $x(k)$ and $y(k)$

1. Apply the definition to signal $x(k)$.
2. Apply the definition to signal $y(k)$.
3. Divide 2 by 1 to get the TRANSFER FUNCTION.

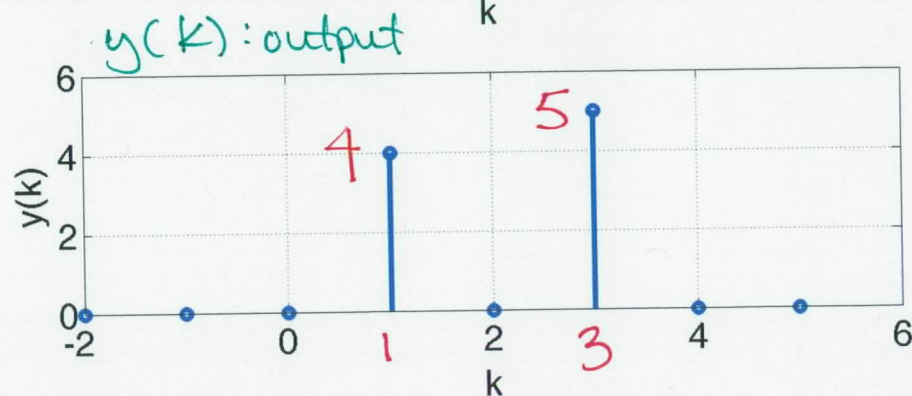


$$G(z) = \frac{Y(z)}{X(z)}$$



$$\sum_{k=-\infty}^{\infty} (x_k \cdot z^{-k})$$

$$\begin{aligned} Z(x(k)) &= 10z^{-1} + 11z^{-2} + 12z^{-3} \\ &= \frac{10}{z} + \frac{11}{z^2} + \frac{12}{z^3} = \frac{10z^2 + 11z + 12}{z^3} \end{aligned}$$

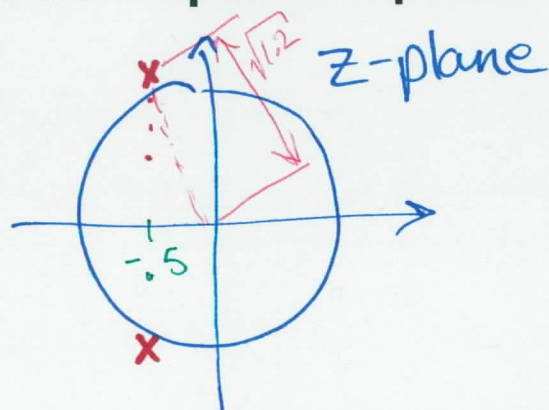


$$\begin{aligned} Z(y(k)) &= 4z^{-1} + 5z^{-3} \\ &= \frac{4}{z} + \frac{5}{z^3} = \frac{4z^2 + 5}{z^3} \end{aligned}$$

$$\therefore G(z) = \frac{(4z^2 + 5)(\cancel{z^3})}{(\cancel{z^3})(10z^2 + 11z + 12)}$$

Examples: Find Z xforms for $x(k)$ and $y(k)$

Now, does this impulse response below for this $G(z)$ make sense?



$$G(z) = \frac{(4z^2 + 5)}{(10z^2 + 11z + 12)}$$

$$\text{poles @ } \boxed{z = -\frac{1}{2} \pm .94j}$$

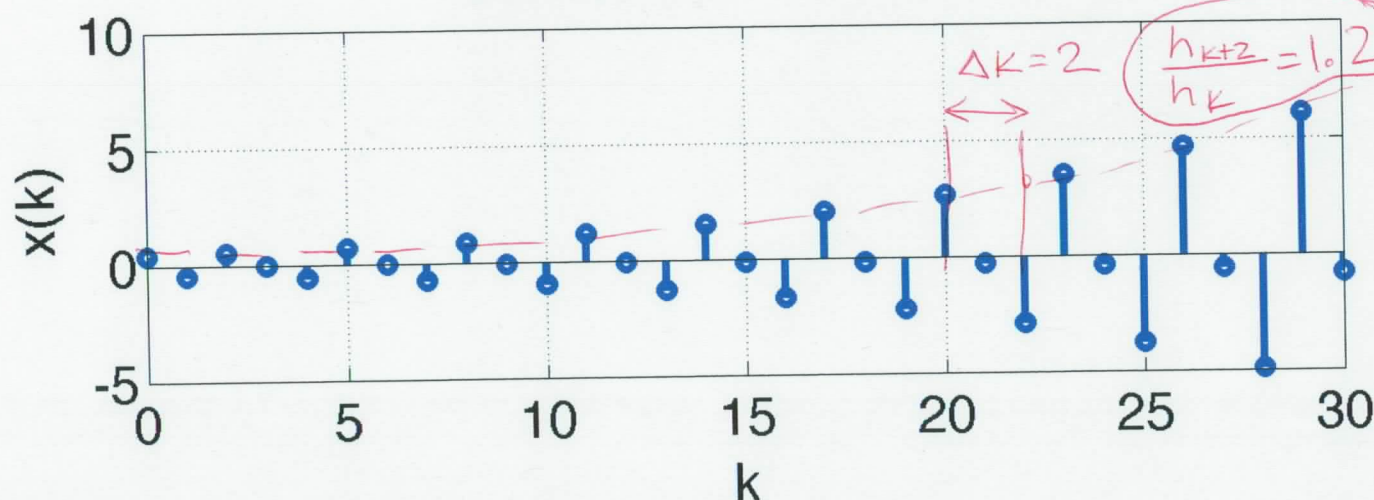
(roots([10, 11, 12]))

char. eqn $\boxed{z^2 + 1.1z + 1.2 = 0}$

$$|z| = \sqrt{1.2} > 1.0$$

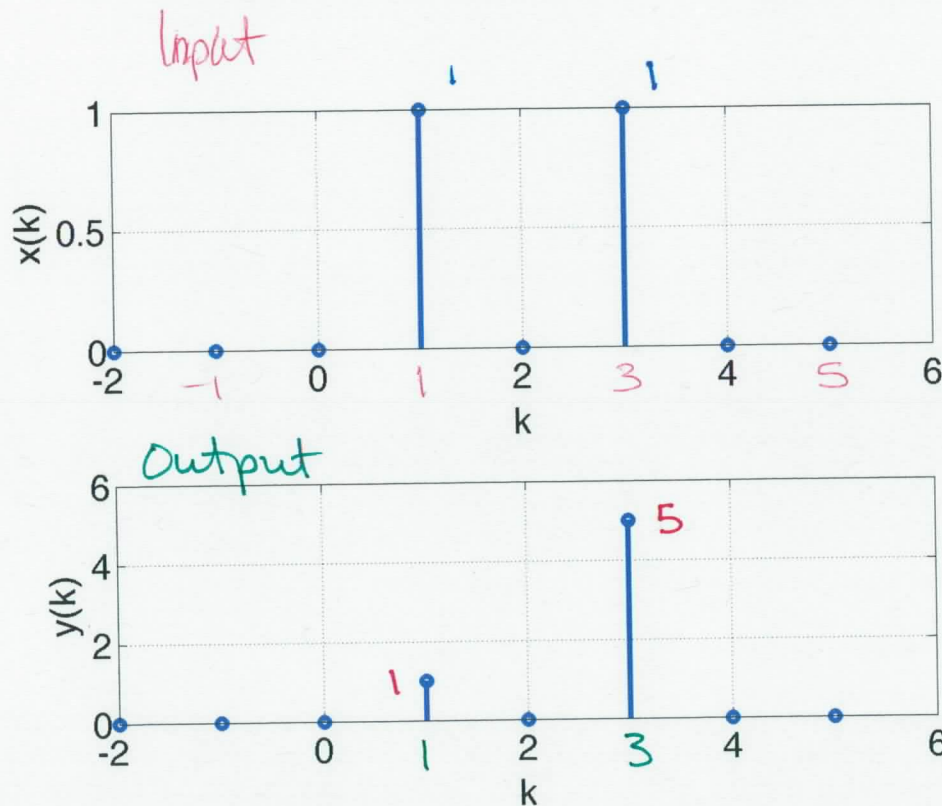
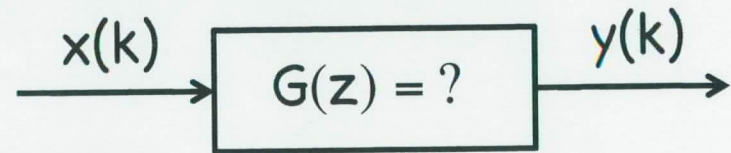
∴ UNSTABLE!

Impulse Response: $x(k) = 1$ for $k=0$, otw $x(k) = 0$



Examples: Find Z xforms for $x(k)$ and $y(k)$

1. Apply the definition to signal $x(k)$.
2. Apply the definition to signal $y(k)$.
3. Divide 2 by 1 to get the TRANSFER FUNCTION.



$$Z(x(k)) = \frac{1}{z} + \frac{1}{z^3} = \frac{z^2 + 1}{z^3}$$

$$Z(y(k)) = \frac{1}{z} + \frac{5}{z^3} = \frac{z^2 + 5}{z^3}$$

$$G(z) = \frac{z^2 + 5}{z^2 + 1} = \frac{z^2}{z^2 + 1} + \frac{5}{z^2 + 1}$$

Now, does this **impulse response** below for this $G(z)$ make sense?

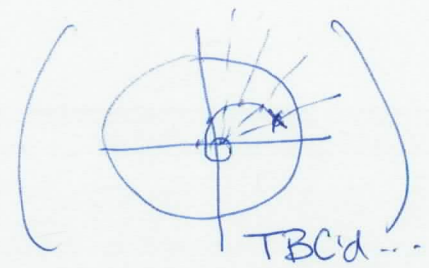
= Marginally Stable

poles: $z = \pm 1 \cdot j$

Diagram of the z -plane showing a unit circle. Poles are marked with 'x' at 1 , -1 , and $-j$. A zero is marked with 'o' at -1 . A dashed line indicates a 90° angle from the positive real axis to the zero at -1 .

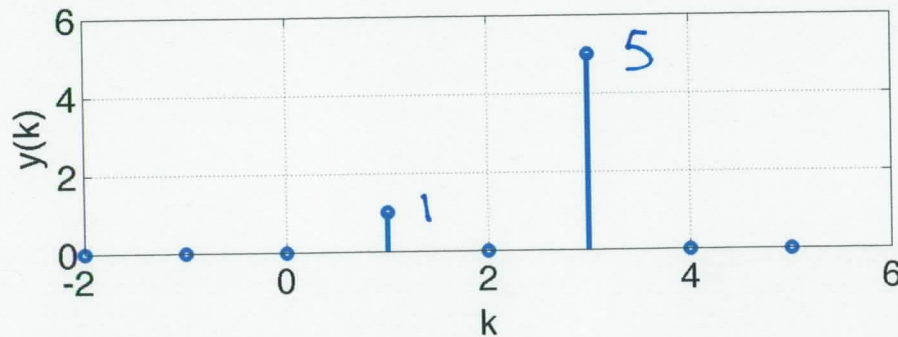
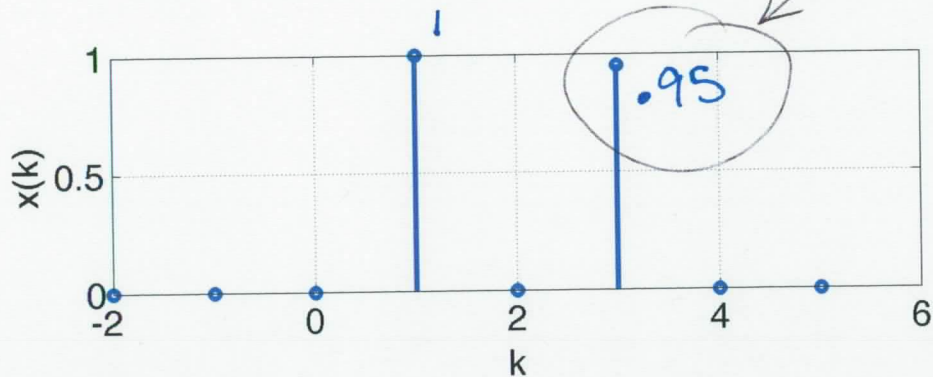
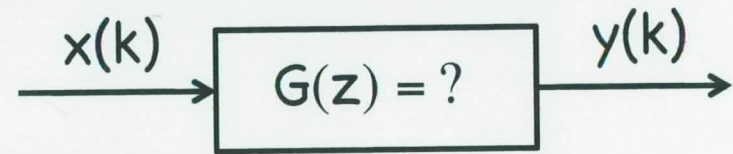
8 samples per cycles

Impulse Response: $x(k) = 1$ for $k=0$, oth $x(k) = 0$



Examples: Find Z xforms for $x(k)$ and $y(k)$

1. Apply the definition to signal $x(k)$.
2. Apply the definition to signal $y(k)$.
3. Divide 2 by 1 to get the TRANSFER FUNCTION.



only changed, compared w/ 2 slides back...

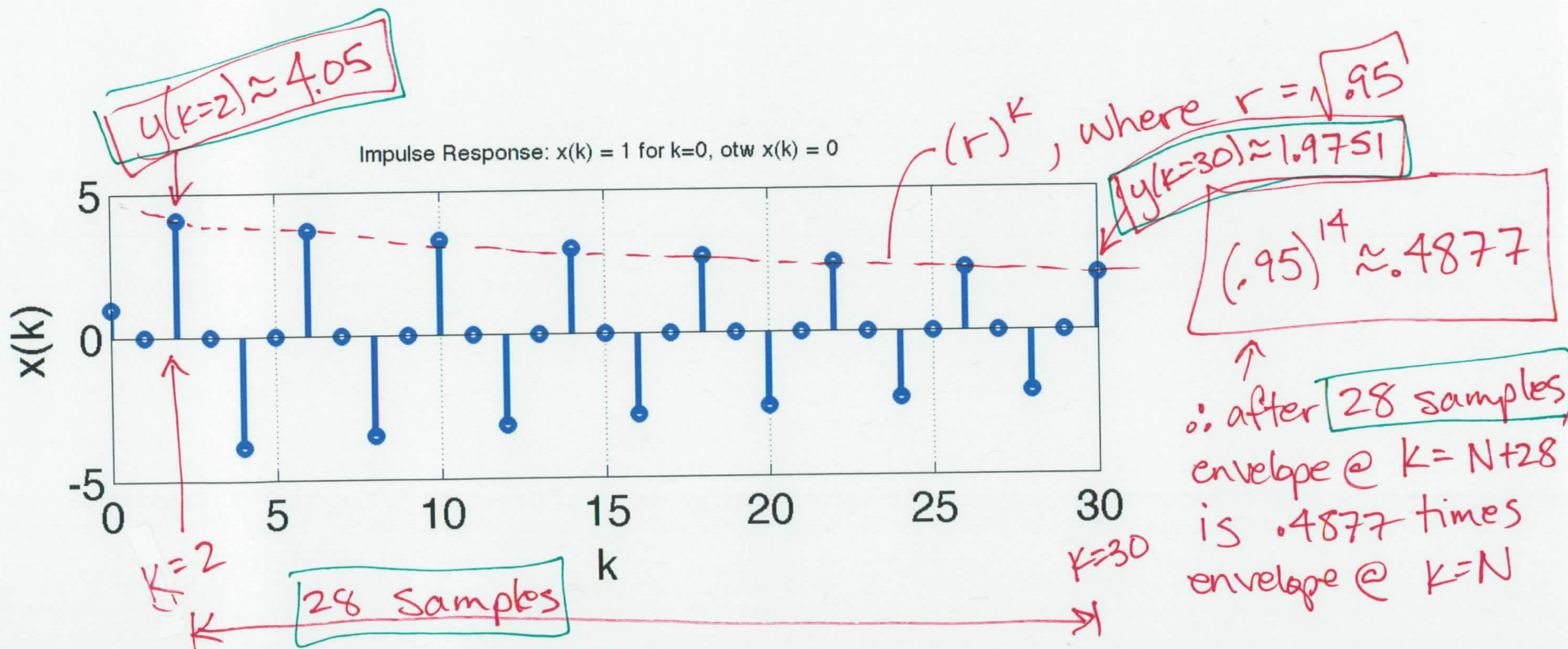
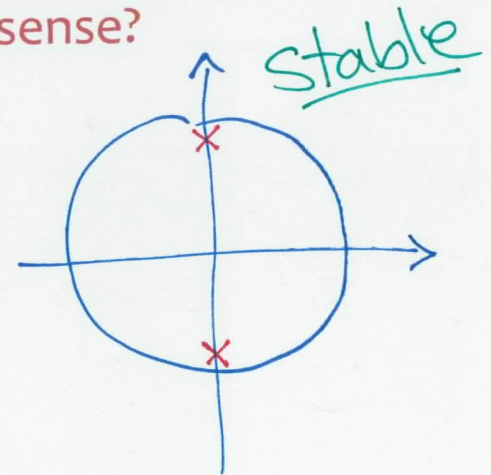
$$G(z) = \frac{z^2 + 5}{z^2 + 0.95}$$

Examples: Find Z xforms for $x(k)$ and $y(k)$

Now, does this impulse response below for this $G(z)$ make sense?

char. eqn. : $z^2 + 0.95 = 0$

poles : $z = \pm \sqrt{.95} j \approx \pm .975 j$



Example: impulse response is a UNIT STEP

$$X(z) \equiv Z\{x(k)\} \equiv \sum_{k=-\infty}^{\infty} x_k z^{-k}$$

Output $y(k)$ are SAMPLES of the IMPULSE response for:

$$G(s) = \frac{1}{s}$$

$$G(z) = \sum_{k=-\infty}^{\infty} (y_k z^{-k})$$

$$= \sum_{k=0}^{\infty} (y_k z^{-k})$$

$$= \sum_{k=0}^{\infty} (1 \cdot z^{-k})$$

$$= z^0 + z^{-1} + z^{-2} + z^{-3} + \dots$$

$$= 1 + \frac{1}{z} + \frac{1}{z^2} + \dots$$

$$= \left(1 + \frac{1}{z} + \frac{1}{z^2} + \frac{1}{z^3} \dots\right)$$

$$\left(1 + \frac{1}{z} + \frac{1}{z^2} + \frac{1}{z^3} \dots\right) \left(1 - \frac{1}{z}\right)$$

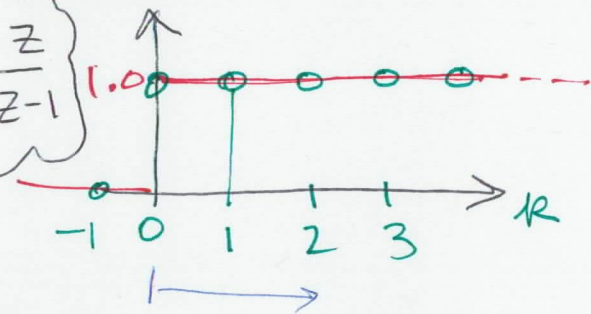
$$1 + \frac{1}{z} + \frac{1}{z^2} + \frac{1}{z^3} \dots$$

$$- \frac{1}{z} - \frac{1}{z^2} - \frac{1}{z^3} \dots$$

$$1 + 0 \checkmark$$

$$\frac{1}{\left(1 - \frac{1}{z}\right)} = \frac{1}{\left(\frac{z-1}{z}\right)} = \frac{z}{z-1}$$

impulse resp. for $G(s)$



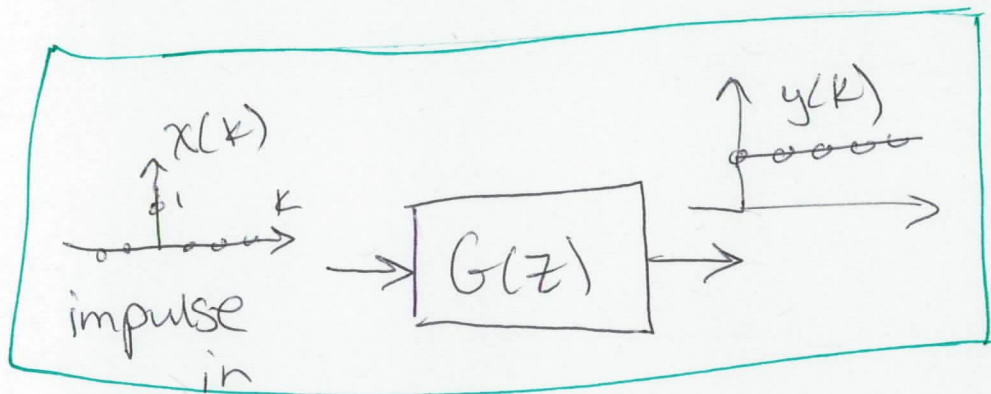
What we want is in the numerator (below)

So, we need the denominator to be 1

SO LONG AS $|z| > 1$ (Region of Convergence...
RoC, TSCd...)

Example: impulse response is a UNIT STEP

So, $\frac{(1 + \frac{1}{z} \dots)}{(1 + \frac{1}{z} \dots)(1 - \frac{1}{z})} = \frac{1}{(1 - \frac{1}{z})} = \frac{z}{z - 1} = G(z)$



Correspondence.

$$\frac{1}{s} = G(s)$$

So, $G(z) = \frac{z}{z-1}$, and $G(z) \equiv \frac{Y(z)}{X(z)}$

$\left(\frac{1}{1 - \frac{1}{z}}\right) = \frac{z}{z-1} \leftarrow y \text{ is } \phi \text{ except for,}$
 $\left(\frac{1}{1 - \frac{1}{z}}\right) = \frac{z}{z-1} \leftarrow x \text{ is } \phi \text{ except for}$

