

Today: Frequency Response: s- vs z-plane

Lecture 6
ECE 147B
Digital Control

Reading: FPW 4.5, 7.5
or: FV 2.8, 4.1-4.6, 6.7

Topics:

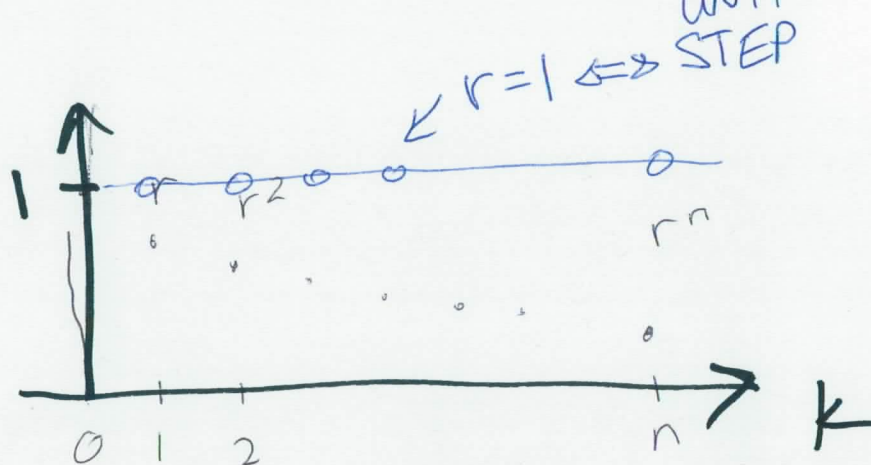
- Time response (Finish from Lecture 5)
- Intuition for z-plane poles
- (Freq. Resp.?)

Next Class: Intro to state space (ss).
- FPW: 4.3.3
or: - FV: 7.1, 7.2

HW2 is
DUE
MONDAY
(AND a Prelab...)

Exponential: $y(k) = r^k$

$$\sum_{k=0}^{\infty} r^k z^{-k} = \sum_{k=0}^{\infty} \left(\frac{r}{z}\right)^k$$



$$\frac{\cancel{\left(1 - \frac{r}{z}\right)}}{\left(1 - \frac{r}{z}\right)} \left(1 + \frac{r}{z} + \left(\frac{r}{z}\right)^2 + \dots\right) = \frac{1}{\left(1 - \frac{r}{z}\right)} = \frac{z}{z-r}$$

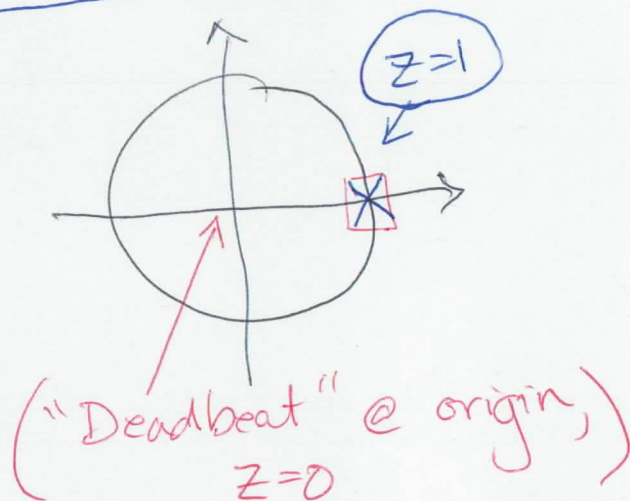
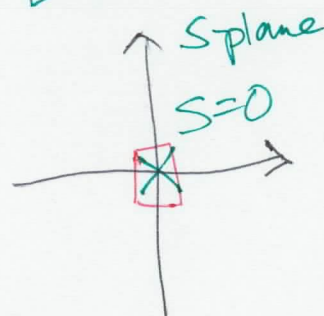
$\left(-\frac{r}{z} - \left(\frac{r}{z}\right)^2 - \dots\right)$

$-\frac{r}{z} \left(1 + \frac{r}{z} + \dots\right)$

$$= \frac{1}{\left(1 - \frac{r}{z}\right)} = \frac{z}{z-r}$$

$$r=1 \Leftrightarrow \frac{z}{z-1}$$

$$\left[\frac{1}{s}\right]$$



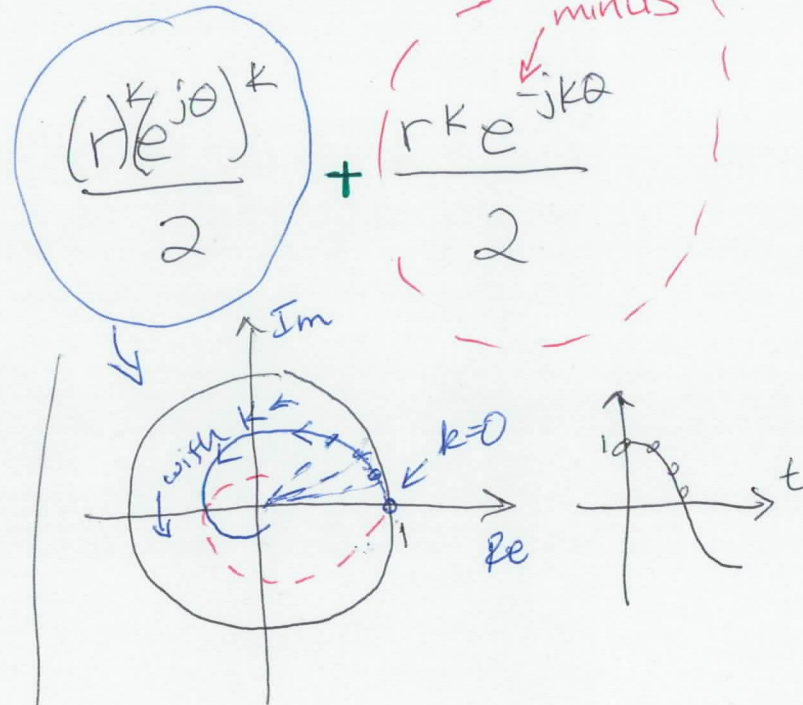
Sinusoid:

$$y(k) = r^k \left(\frac{e^{jk\theta} + e^{-jk\theta}}{2} \right) =$$

$r=1$, sine (not decaying)
(actually a cosine)

$r < 1$ decaying sinusoid
~

$r > 1$ Unstable (growing)
~



→ Z-transform (definition)

$$\sum_{k=0}^{\infty} r^k \left(\frac{e^{jk\theta} + e^{-jk\theta}}{2} \right) z^{-k}$$

Two Parts

$$\left[\frac{1}{2} \right] \left(\frac{1}{1 - \frac{re^{-j\theta}}{z}} \right)$$

$$\frac{1}{2} \sum_{k=0}^{\infty} r^k e^{jk\theta} z^{-k} = \left(\frac{re^{j\theta}}{z} \right)^k * \frac{1}{2}$$

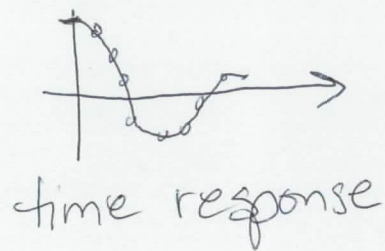
So, we can write this INFINITE SUM

AS: $\left(\frac{1}{1 - \frac{re^{j\theta}}{z}} \right) * \frac{1}{2}$ same trick

Last page ...

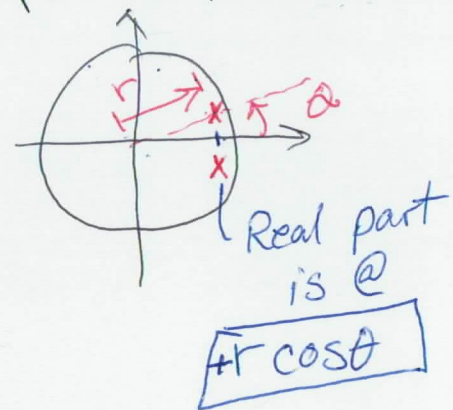
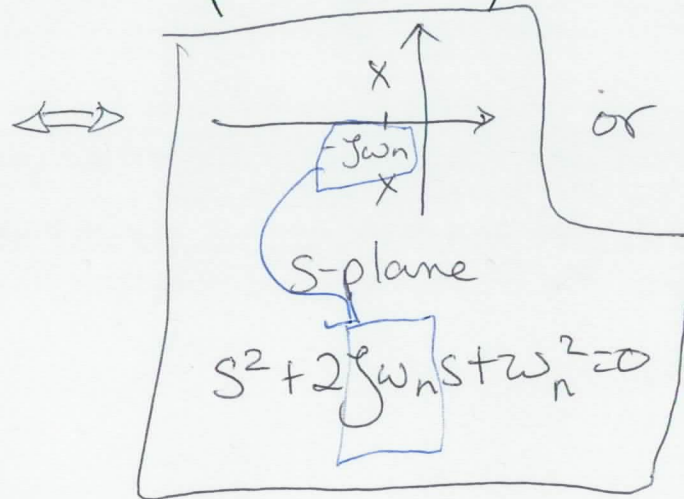
$$\sum_{k=0}^{\infty} \left(\frac{r}{z} \right)^k \Rightarrow \frac{1}{(1 - \frac{r}{z})}$$

Sinusoid:



$$y(k) = r^k \left(\frac{e^{jk\theta} + e^{-jk\theta}}{2} \right)$$

$$\Leftrightarrow Y(z) = \left(\frac{z^2 - r(\cos\theta)z}{z^2 - 2r(\cos\theta)z + r^2} \right)$$



Combining terms from last page...

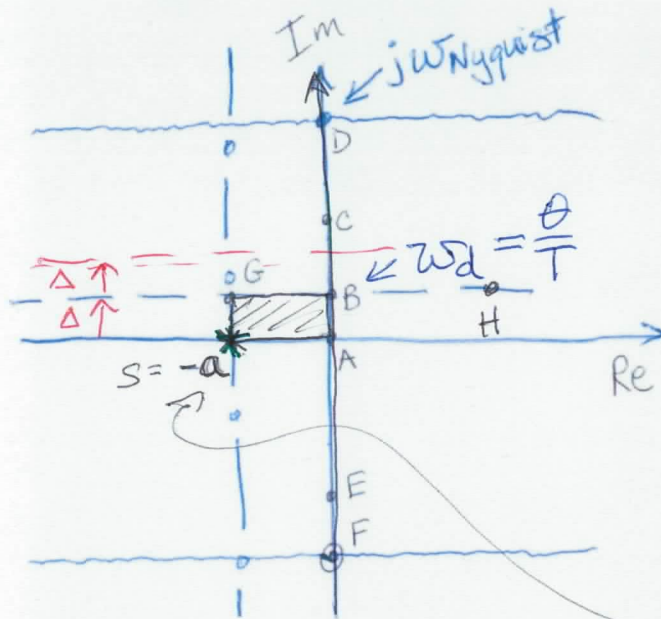
$$Y(z) = \left(\frac{1}{\left(1 - \frac{re^{j\theta}}{z}\right)} + \frac{1}{1 - \frac{re^{-j\theta}}{z}} \right) \frac{1}{2}$$

$$= \left(\frac{z(z - re^{j\theta})}{(z - re^{j\theta})(z - re^{-j\theta})} + \frac{(z - re^{-j\theta})}{(z - re^{-j\theta})(z - re^{j\theta})} \right) \frac{1}{2}$$

$$= \frac{1}{2} \frac{(z^2 - zre^{j\theta}) + (z^2 - zre^{-j\theta})}{z^2 - [zre^{j\theta} + zre^{-j\theta}] + r^2 e^{(j\theta - j\theta)}} = \frac{2z^2 - 2r(\cos\theta)z}{(\dots)2}$$

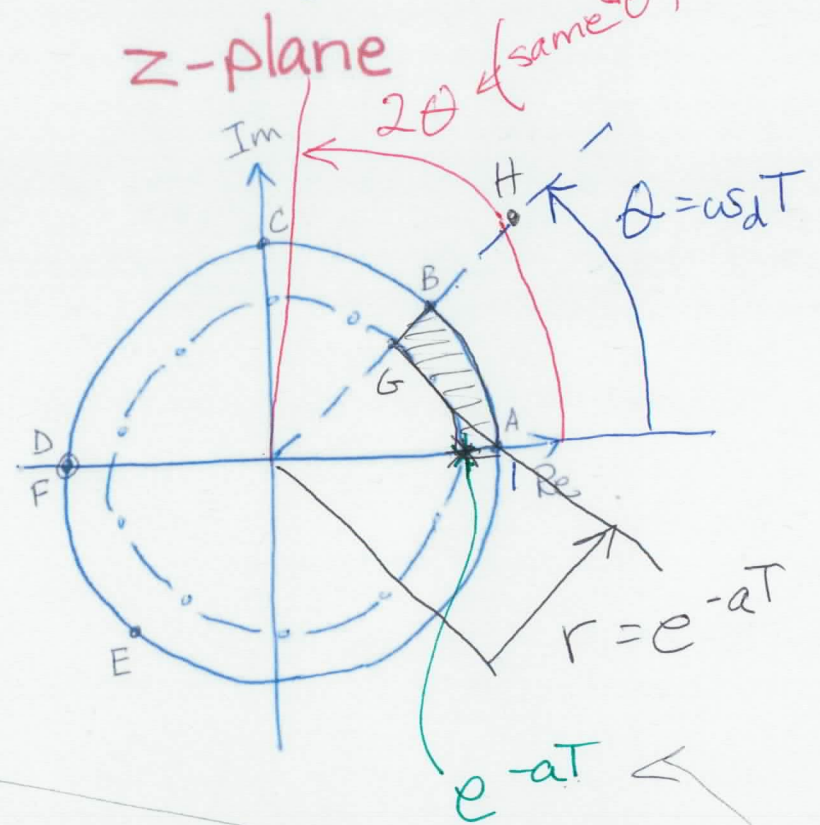
Pole Correspondence:

S-plane



(Sampling time T)

z-plane



$$S = -\underline{a} + \underline{\omega_d}j$$

$\tau = \frac{1}{a}$, decay env.
 $\omega_d \rightarrow$ damped nat. freq.

$$Z = e^{(-\underline{a} + \underline{\omega_d}j)T} = e^{-aT} e^{j\omega_d T}$$

$= \underline{r}$ tells " θ "

on z-plane,

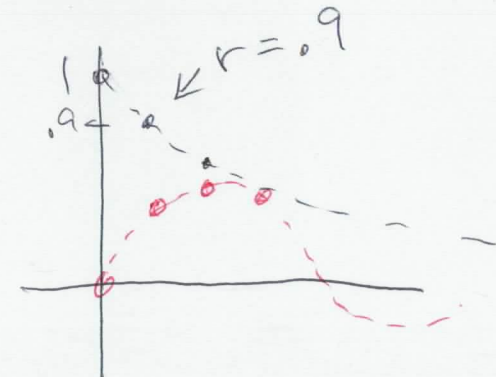
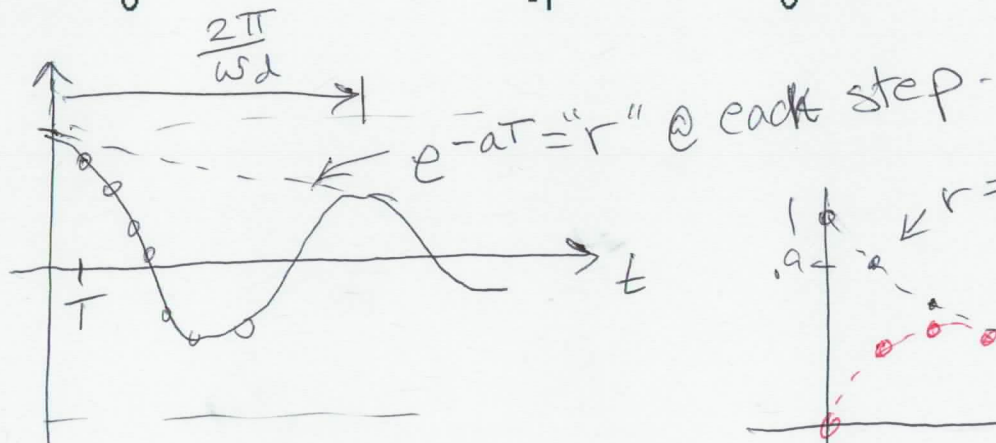
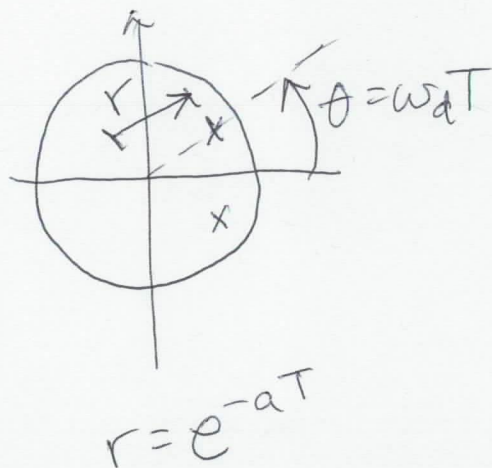
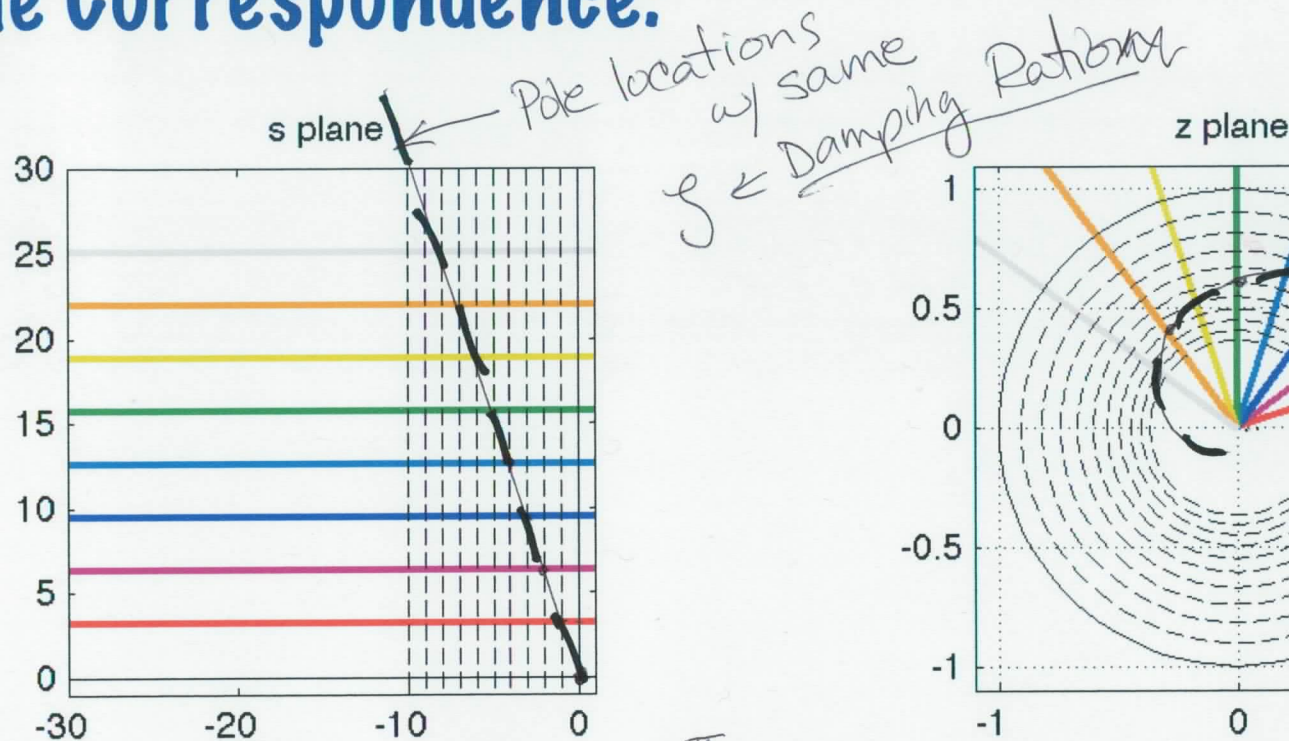
"pole-zero matching"

e.g.
 $S = bj$
 $\downarrow$
 $z = e^{bjT}$

$$Z = e^{sT}$$

$s = -a, 0$
 $z = e^{-aT}$

Pole Correspondence:



Example: $G(z) = Y(z)/Z(z) = z/(z^2 - z + 0.5)$

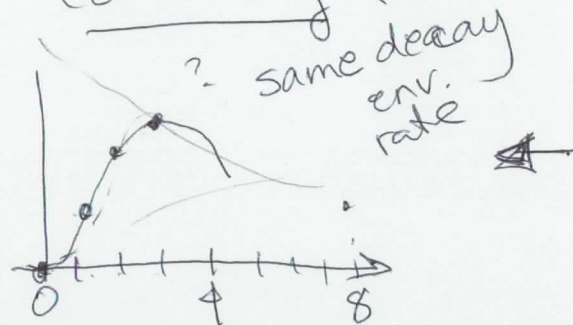
What would a step response look like?

Final value to a unit step in?

$$\lim_{z \rightarrow 1} \frac{z}{z^2 - z + 0.5} \cdot \frac{z}{z-1} \leftarrow \text{unit step in.}$$

$$\frac{1}{1 - 1 + 0.5} = 2 \text{ F.V.}$$

Combining?

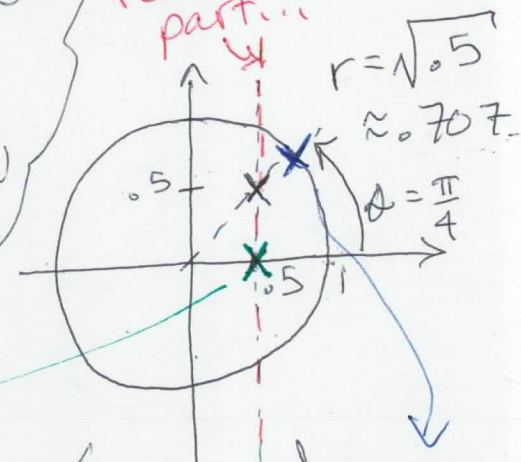


$$\frac{z}{z^2 - z + 0.5}$$

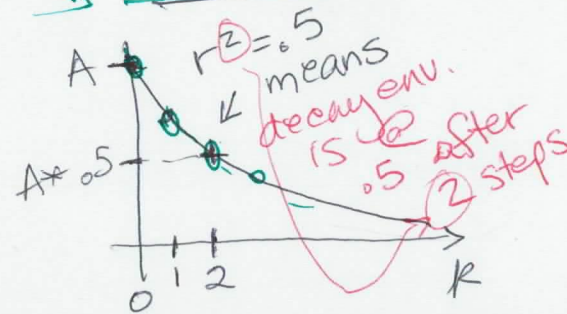
negative z
the real part...

r^2 (like ω_n^2)

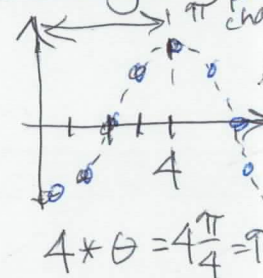
Thinking about poles ONLY first



Real Part



Imag Part



Example: $G(z) = Y(z)/X(z) = z/(z^2 - z + 0.5)$

Second look,
let's write the diff eq. $\rightarrow$

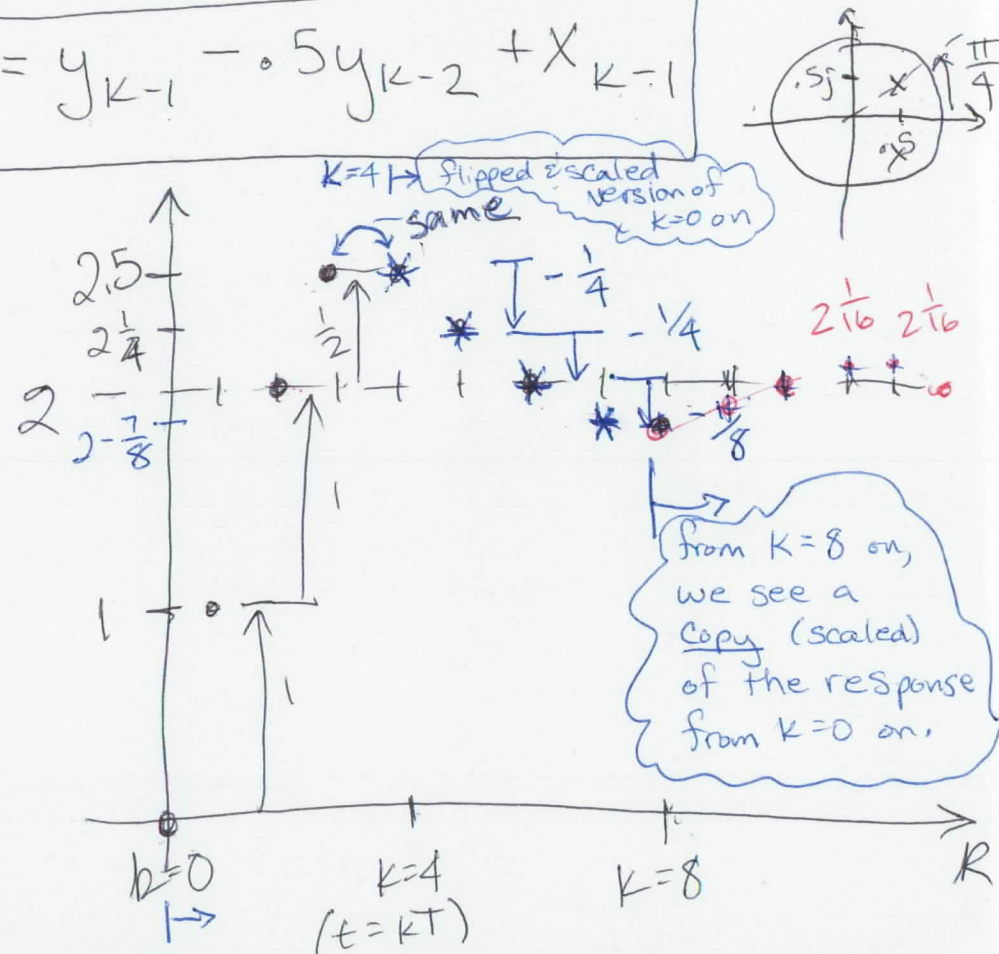
$$\frac{Y}{X} = \frac{z}{z^2 - z + 0.5}$$

$$y_{k+2} - y_{k+1} + 0.5y_k = X_{k+1}$$

k	X	y
-1	0	0
0	1	0
1	1	1
2	1	2
3	1	2.5
4	1	2.5
5	1	2.25
6	1	2
7	1	1.75
8	1	1.5

$1 + 1 - \frac{0}{2}$
 $1 + 2 - \frac{1}{2}$
 $1 + 2.5 - 1$
 $1 + 2.5 - 1.25$
 $1 + 2.25 - 1.25$
 $1 + 2 - 1.125$
 $1 + 1.75 - 1$

$$y_k = y_{k-1} - 0.5y_{k-2} + X_{k-1}$$



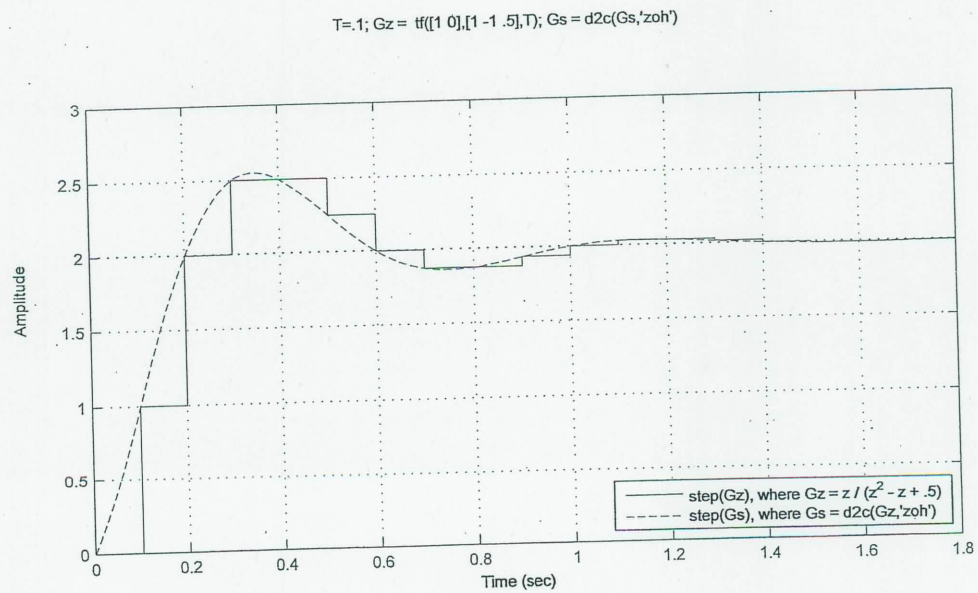
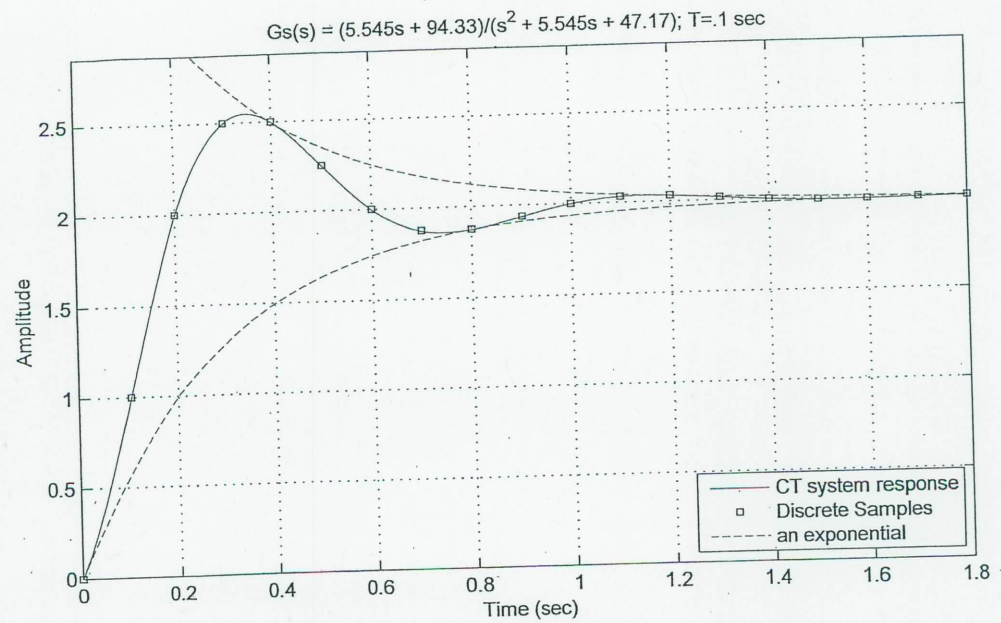


Figure 4.26
Corresponding lines in
the s-plane and the
z-plane according to
 $z = e^{sT}$

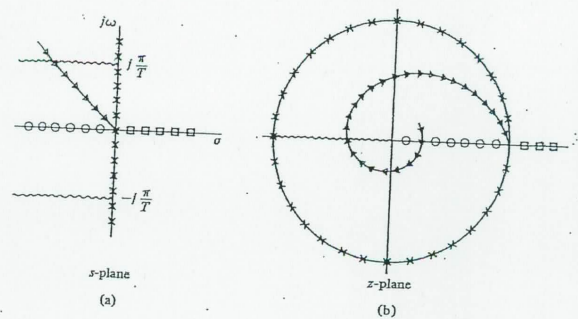


Figure 2.5
Time functions
associated with points in
the s-plane

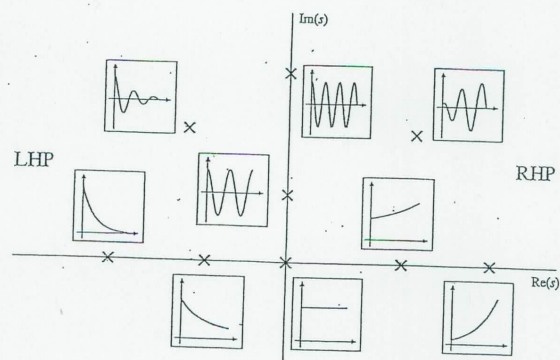


Figure 4.25
Time sequences associated with pole locations in the z-plane

